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This is the more practical approach to engineering mechanics that deals mainly withtwo-dimensional problems, since these comprise the great majority of engineering situationsand are the necessary foundation for good design practice. The format developedfor this textbook, moreover, has been devised to benefit from contemporary ideas ofproblem solving as an educational tool. In both areas dealing with statics and dynamics,theory is held apart from applications, so that practical engineering problems, whichmake use of basic theories in various combinations, can be used to reinforce theoryand demonstrate the workings of static and dynamic engineering situations.In essence a traditional approach, this book makes use of two-dimensional engineeringdrawings rather than pictorial representations. Word problems are included in the latterchapters to encourage the student's ability to use verbal and graphic skills interchangeably.SI units are employed throughout the text.This concise and economical presentation of engineering mechanics has been classroomtested and should prove to be a lively and challenging basic textbook for two oneseimestercourses for students in mechanical and civil engineering. Applied EngineeringMechanics: Statics and Dynamics is equally suitable for students in the second or thirdyear of four-year engineering technology programs.

Statics of particles -- Rigid bodies: equivalent systems of forces -- Equilibrium of rigid bodies -- Distributed forces: centroids and centers of gravity -- Analysis of structures -- Internal forces and moments -- Friction -- Distributed forces: moments of inertia -- Method of virtual work -- Kinematics of particles -- Kinetics of particles: Newton's second law -- Kinetics of particles: energy and momentum methods -- Systems of particles -- Kinematics of rigid bodies -- Plane motion of rigid bodies: forces and accelerations -- Plane motion of rigid bodies: energy and momentum methods -- Kinetics of rigid bodies in three dimensions -- Mechanical vibrations

Dynamic objects move in mysterious ways. Their analysis is a difficult subject involving matrices, differential equations and the complex algebra of oscillatory systems. However, in this textbook, the author draws on his long experience of designing autopilots, robots for nuclear inspection and agricultural machine guidance to present the essentials with a light touch. The emphasis is on a deep understanding of the fundamentals rather than rote-learning of techniques. The inertia tensor is presented as a key to understanding motion ranging from boomerangs to gyroscopes. Chains of transformations unravel the motion of a robot arm. To help the reader visualise motion, ranging from unbalanced rotors to vibrating systems with multiple modes and damping, there are abundant simulation examples on a linked website. These will run in any web browser, while their simple code is on open view for modification and experimentation. They show that nonlinear systems present no problems, so that friction damping can be modelled with ease. A particular problem for mechanical engineers is that the vibration topics encroach on the territory of the electrical engineer. State variables open up control theory while the solution of differential equations with sinusoidal inputs is simplified by an understanding of sine-waves as complex exponentials. The linked web site has several areas of mathematics revision to help. A final chapter pokes fun at the misrepresentation of dynamics in cinema productions.